

OPL CPLEX tutorial: How to solve an optimization problem in IBM ILOG CPLEX Optimization studio

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What is “CPLEX”, “IDE” and “OPL”

- **Optimization Programming Language (OPL)**
 - A simple and influential modeling language for optimization problems
- **CPLEX**
 - A powerful solver for LP/QP/CP, consequently, MIP, MIQP, etc. from IBM.
- **CPLEX Studio IDE**
 - A user-friendly interface for the CPLEX solver and the CP optimizer
 - Other platforms capable of extracting the CPLEX solver includes;
 - Microsoft Solver Excel, Matlab, CPLEX Interactive Optimizer, Python API, web (online servers such as www.neos-server.org)
 - Concert Technology, Callable Library
- **Integrated Development Environment (IDE)**
 - An IBM product to edit OPL models, solve problems, display results, organize models, data and settings into configurations
- **How to download IBM ILOG CPLEX Optimization Studio (Version 12.6.3) [free for students](#)**
 - <http://www-01.ibm.com/support/docview.wss?uid=swg24041278>

How to code an optimization problem in CPLEX Studio IDE

- **Creating a new project:** to associate .mod, .dat and .ops files
- **Creating a new .mod file** (tutorial-production-1)
 1. Ranges
 2. Decision variables (↙)
 3. Input values (↖)
 4. Objective function
 5. Constraints

Tricks for Frequently Used Arguments in .mod

- $\sum_{j \in J} x_{ij} = 1 ; \quad \forall i \in I$

```
forall(i in I)
    sum(j in J) x[i,j] == 1;
```

- $x_{ij} \leq 1 ; \quad \forall i \in I , j \in J$

```
forall(i in I, j in J)
    x[i,j] <= 1;
```

Tricks for Frequently Used Arguments in .mod

- $x_{ij} \geq 0 ; \forall i \in I , j \in J \setminus \{2\}$

```
forall(i in I, j in J: j != 2)
    x[i,j] >= 0;
```

- $\sum_{i \in I \setminus \{1\}} \sum_{j \in J} x_{ij} > 0$

```
sum(i in I: i != 1, j in J) x[i,j] > 0;
```

How to code an optimization problem

- **Creating a new project:** to associate .mod, .dat and .ops files
- **Creating a new .mod file**
 1. Ranges
 2. Decision variables (↙)
 3. Input values (↖)
 4. Objective function
 5. Constraints
 6. Execution (optional) (tutorial-production-3)
- For more flexibility → **Creating a new .dat file**
 - Be careful about configuration (tutorial-production-2)
- For more flexibility → **Having several configurations** (tutorial-production-5)

How to have connection with Excel

- For more flexibility → **Linkage with an Excel file** (tutorial-production-4)
 - Input
 1. SheetConnection `functionName` (“excel file name”);
 2. Data from SheetRead (`functionName`, “sheetname!cells”);
 - Output
 1. SheetConnection `functionName` (“excel file name”);
 2. Data to SheetWrite (`functionName`, “sheetname!cells”);
- **Generalized Programming** (tutorial-production-6)

Tricks:

- **3-dimensional table in Excel**

(tutorial-production-multi period)

- create a 2-dimensional sub-table and input the data to it
- create a new range for the sub-table
- create the main table by enumerating sub-table

How CPLEX solves problems

- Solves linear programming (LP) problems using simplex/dual simplex/interior point methods
- Solves network flow problems using the network simplex method
- Solves convex quadratic programming (QP) using interior point methods
- Solves pure integer (IP) and mixed integer programming problems by using branch and cut (B&C) methods

How CPLEX solves a MIP problem

- **Branch and Cut (B&C)**
 - B&B combined with cutting planes methods
 - Dynamic programming
- **CP Optimizer**
 - Constraints Propagation
 - Constructive Search techniques

Constraint Propagation

- Tries to reduce the domain of decision variables, which leads in reduction in search space;

$$x + y \leq 8$$
$$x, y \in \{1,2,3,4,5,6,7,8,9,10\}$$

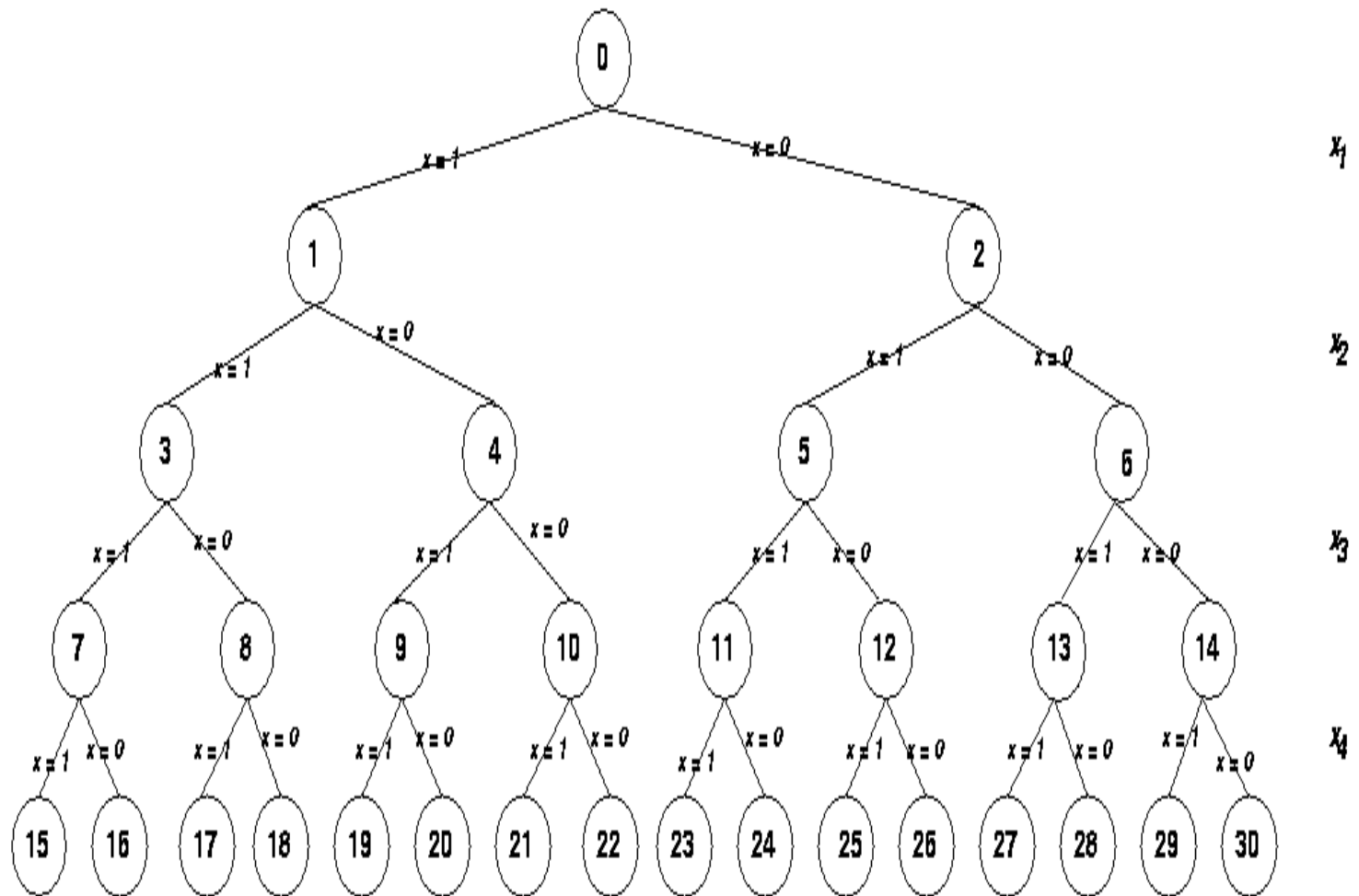
Initial Propagation:

$$x \in \{1,2,3,4,5,6,7,8,9,10\}$$

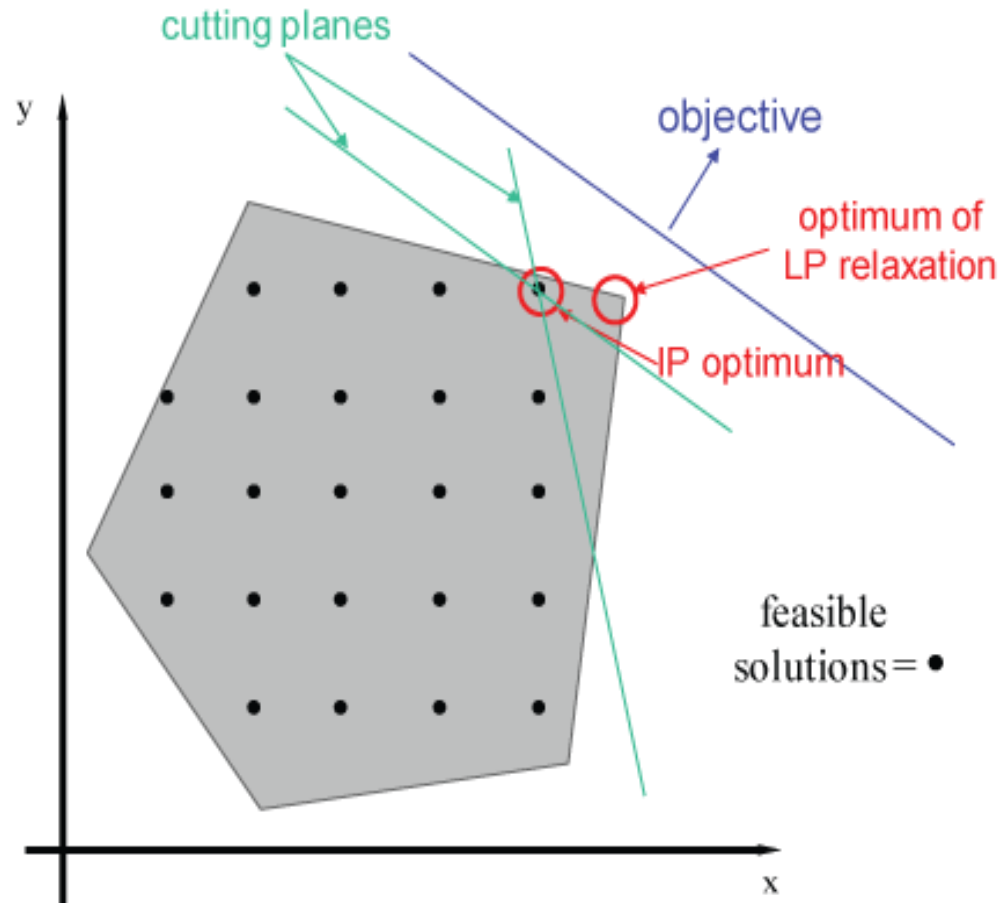
$$y \in \{1,2,3,4,5,6,7,8,9,10\}$$

- Initial Constraint Propagation
- Constraint Propagation during Search

B&B



Cutting Planes



Cutting Planes

Setting configuration

- Set LP format to gain B&C information
- Decide about relaxed variables/constraints
- Decide about B&C tree:
 - MIP dynamic search switch
 - Node selection
 - Branching direction

How to interpret “Engine log” and “Statistics” taps

- ❖ Integrality relaxed problems are usually solved by dual simplex
 - How to control it
- How to control MIP tolerances
- How to control MIP limits
- How to control MIP Strategy
 - How to set B&C tree structure
 - How to obtain Upper Bound (UP)
- How to control MIP cuts

Formulation Tightness and CPLEX Approach

- A Capacitated Facility Location Problem (CFLP)

$$\text{Min } z = \sum_{j \in J} f_j y_j + \sum_{i \in I} \sum_{j \in J} c_{ij} x_{ij}$$

s. t.:

$$\sum_{i \in I} d_i x_{ij} \leq \mu_j y_j \quad ; \quad \forall j \in J$$

$$\sum_{j \in J} x_{ij} \geq d_i; \quad \forall i \in I$$

Formulation Tightness and CPLEX Approach

- Valid inequalities for CFLP;

$$\sum_{j \in J} x_{ij} \geq d_i \quad \rightarrow \quad \sum_{j \in J} x_{ij} = d_i$$

$$\sum_{i \in I} x_{ij} \leq y_j \quad ; \quad \forall j \in J$$

$$\sum_{j \in J} \mu_j y_j \geq \sum_{i \in I} d_i x_{ij}$$

Advanced Programming Techniques

- Pre-solving
- Parallel Optimizers

Why using CPLEX Studio IDE

- A user-friendly interface for the CPLEX solver and the CP optimizer
- No need to programming languages
- No need to define directories, linkers, preprocessors, etc.

Drawback of CPLEX Studio IDE

We have to use Concert Technology/Callable Library to have;

- **Advanced MIP Control Interface (CallBack)**
 - Customized solution method (Solve / Incumbent CallBack)
 - Full control of solution method (MIP Control CallBack)
 - Stopping procedure for any inspection (Selection CallBacks)
 - Adding user-cuts / lazy-constraints (Cut CallBack)
 - ...

The most powerful interfaces for CPLEX solver and CP optimizer with full control;

- ❖ **Concert Technology:** for C++/Java/.NET users
- ❖ **Callable Library:** for C users

Suggested References

- **Implementation**

- Help – IBM ILOG CPLEX Optimization Studio
- IBM ILOG CPLEX Optimization Studio OPL Language User's Manual, IBM
- <https://www.ibm.com/support/knowledgecenter/>

- **Theoretical Concepts**

- Wolsey, Integer Programming
- 50 Years of Integer Programming 1958-2008
- Fischetti, Glover, Lodi, The Feasibility Pump
- Nemhauser, Integer Programming and Combinatorial Optimization



Thank you for attention