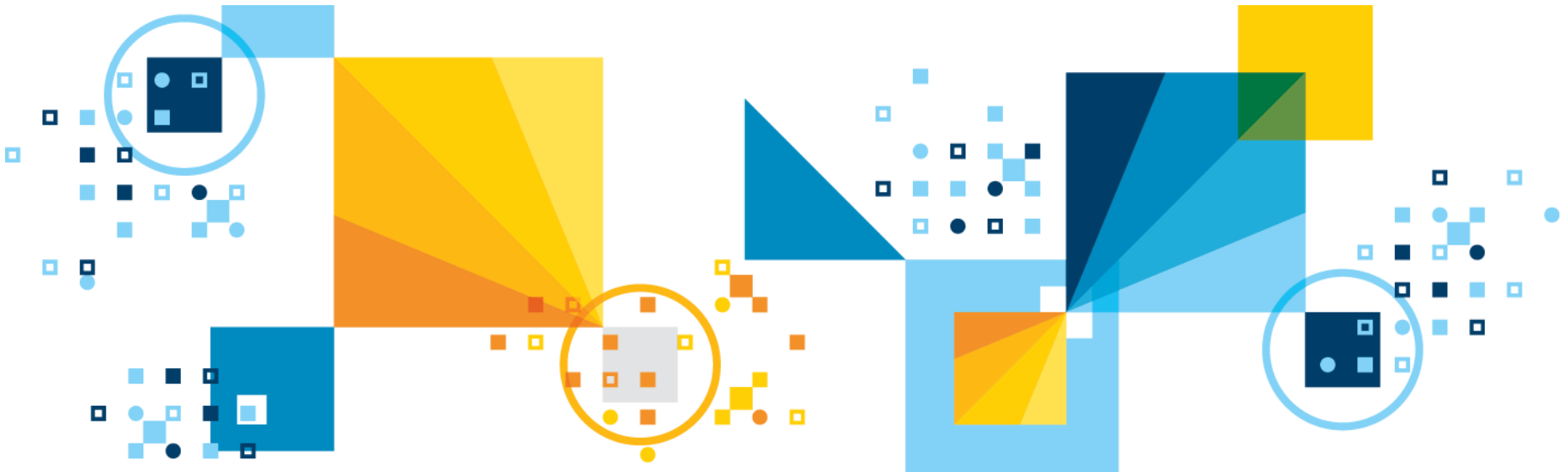


Benders Decomposition in CPLEX 12.7.0

@CPLEX school 2017, Montreal



Benders decomposition: quick literature review

- Originally proposed for MILP by Benders [Benders, 1962]
- Generalized to convex MINLP by Geoffrion [Geoffrion, 1972]
- One of the methods of choice for large size stochastic LP and MILP
 - See, e.g., [Van Slyke and Wets, 1969, Carøe and Tind, 1998, Bodur et al., 2016, Hassanzadeh and Ralphs, 2016]
- But also effective on non-stochastic problems, as e.g.,
 - Network design
 - See, e.g., [Costa, 2006] for a survey paper
 - Linear and quadratic facility location
 - [Fischetti et al., 2015, Fischetti et al., 2016]
- **Benders decomposition in CPLEX 12.7.0**
 - Only MILP supported (no MIQP or MIQCP)

Benders decomposition: the basic idea

$$\text{(or-MILP)} \left\{ \begin{array}{l} \min \quad c^T x + d^T y \\ A x \geq b \\ T x + B y \geq e \\ x \geq 0, x \text{ integer} \\ y \geq 0 \end{array} \right.$$

x : Primary variables
(integer or continuous)

y : Secondary variables
(continuous)

Linking constraints

▪ Benders reformulation:

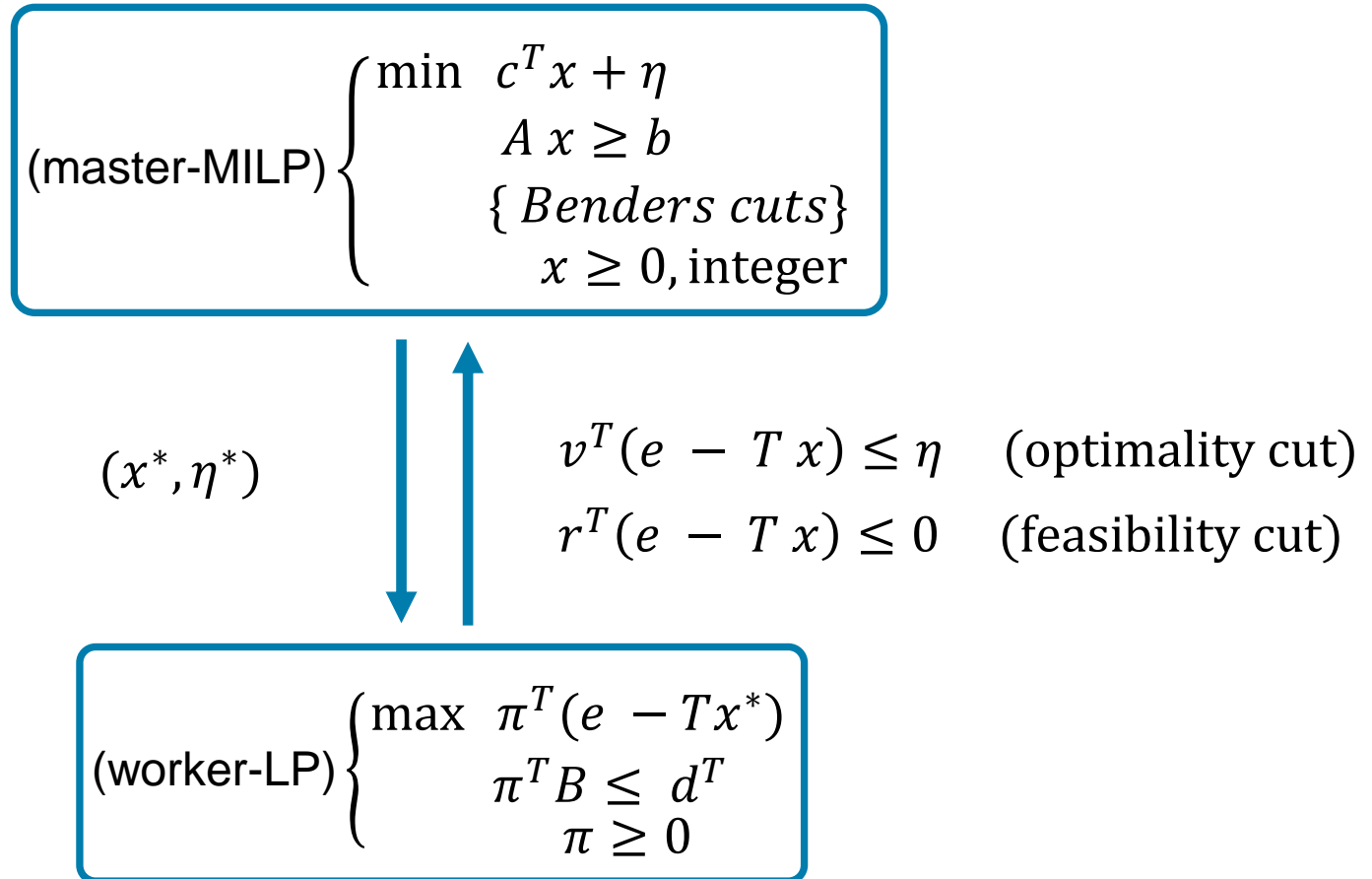
- Add variable $\eta = d^T y$ to represent the contribution of y to the objective function
- Project onto the (x, η) space:

$$\text{(re-MILP)} \left\{ \begin{array}{l} \min \quad c^T x + \eta \\ A x \geq b \\ v^T (e - T x) \leq \eta, \quad v \in V \\ r^T (e - T x) \leq 0, \quad r \in R \\ x \geq 0, \text{ integer} \end{array} \right.$$

V, R : vertices and extreme rays of
 $Q = \{\pi \in \mathbb{R}^m : \pi^T B \leq d^T, \pi \geq 0\}$

Benders decomposition: the basic idea

- The reformulated problem (re-MILP) can be solved by separating Benders cuts on the fly:



Workers decomposition

- In some relevant cases (e.g., Stochastic MILP), the linking constraints decompose in $k \geq 2$ blocks

$$[T \quad B] = \begin{bmatrix} T_1 & B_1 & 0 & \dots & 0 \\ T_2 & 0 & B_2 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ T_k & 0 & 0 & \dots & B_k \end{bmatrix}$$

- And (or-MILP) reads as

$$(\text{or-MILP}) \left\{ \begin{array}{l} \min \quad c^T x + d_1^T y_1 + \dots + d_k^T y_k \\ A x \geq b \\ T_i x + B_i y_i \geq e_i, \quad i = 1, \dots, k \\ x \geq 0, x \text{ integer} \\ y_i \geq 0, \quad i = 1, \dots, k \end{array} \right.$$

Workers decomposition

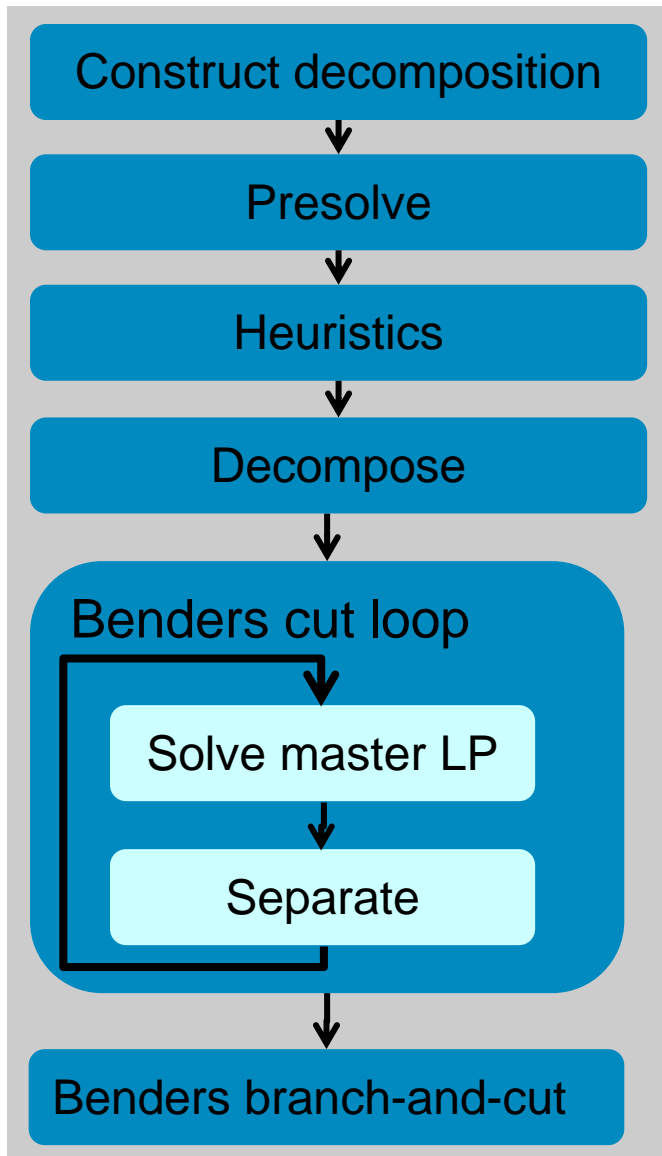
- In Benders reformulation, each block can be decomposed independently of the others

$$\text{(re-MILP)} \left\{ \begin{array}{l} \min \quad c^T x + \eta_1 + \dots + \eta_k \\ A x \geq b \\ v_i^T (e_i - T_i x) \leq \eta_i, \quad v_i \in V_i \quad (i = 1, \dots, k) \\ r_i^T (e_i - T_i x) \leq 0, \quad r_i \in R_i \quad (i = 1, \dots, k) \\ x \geq 0, \text{ integer} \end{array} \right.$$

 (x^*, η_i^*)
 $v_i^T (e_i - T_i x) \leq \eta_i \quad (\text{optimality cuts})$
 $r_i^T (e_i - T_i x) \leq 0 \quad (\text{feasibility cuts})$

$$\text{(worker-LP)}_i \left\{ \begin{array}{l} \max \quad \pi^T (e_i - T_i x^*) \\ \pi^T B_i \leq d_i^T \\ \pi \geq 0 \end{array} \right.$$

CPLEX Benders MIP Solver



- Decomposition
 - Provided through annotation APIs, or
 - Automatic
- Presolve
 - Preserves the block structure
- Heuristics
 - On the complete MIP
 - May run in parallel to the Benders cut loop
- Benders cut loop
 - Tries to solve the LP relaxation of projected MIP to optimality
- Benders branch-and-cut
 - Benders cuts must be separated as lazy constraints, to cut integer solutions
 - Also separated for fractional solutions

Using Benders: annotation APIs and “benders strategy” parameter

- Specify the block structure with (new) CPLEX annotation APIs
 - For each variable, specify the block which the variable belongs to
 - $i = 0$ for primary (i.e., master) variables x
 - $i \geq 1$ for secondary variables in block i (i.e., variables y_i)
 - Available with all CPLEX APIs
 - Can be used to write/read annotation to/from an xml file
- Or ask CPLEX to automatically construct a (simple) decomposition

Parameter CPXPARAM_Benders_Strategy	
1 (USER)	Use block decomposition as provided from the annotation.
2 (WORKERS)	Use given annotation only to identify primary (i.e., master) variables x and secondary variables y . Automatic workers decomposition: if possible, second stage matrix B is decomposed in disjoint blocks.
3 (FULL)	Ignore any given annotation and automatically construct a simple decomposition: integer variables in master block, continuous variables in workers, plus workers decomposition.
-1 (OFF)	Ignore given annotation (if any) and run conventional branch and cut.
0 (AUTO), default	If no annotation is provided, apply conventional branch and cut (no Benders). If annotation is provided, do the same as strategy 2 (WORKERS).

Using Benders with CPLEX interactive

Read decomposition from annotation

```
read myprob.lp
read myanno.ann
optimize
```

OR

Let CPLEX decompose the model

```
read myprob.lp
set benders strategy 3
optimize
```

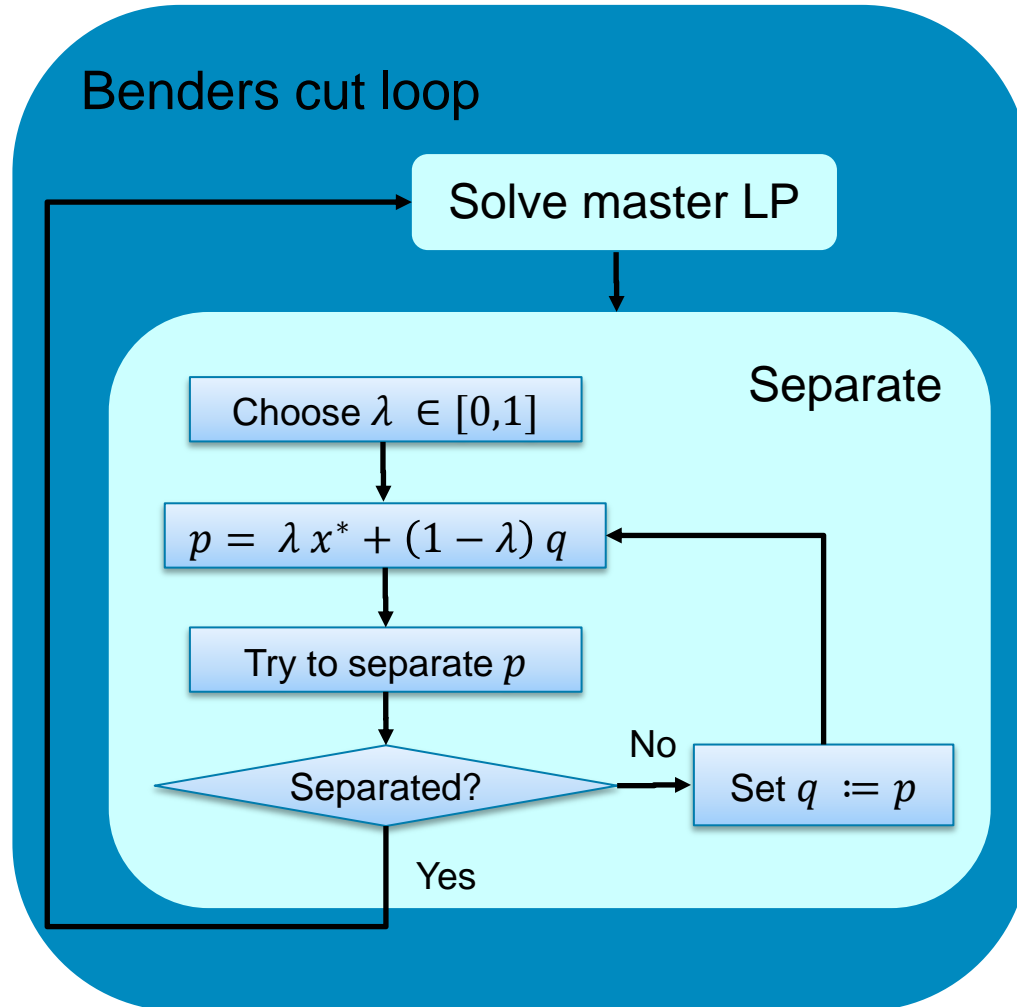
	Parameter CPXPARAM_Benders_Strategy
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Benders cuts separation: two-stage approach

- Given (x^*, η_i^*) , separate cuts for each block $i = 1, \dots, k$
 - Two-stage approach separation in the primal space
 - Normalization for feasibility cut selection, similar to [\[Fischetti et al., 2010\]](#)

Stage	Cut Generating LP (CGLP)	Dual of	Cut
1	$\begin{cases} \min d_i^T y_i \\ B_i y_i \geq e_i - T_i x^* \\ y_i \geq 0 \end{cases}$	$\begin{cases} \max \pi^T (e_i - T_i x^*) \\ \pi^T B_i \leq d_i^T \\ \pi \geq 0 \end{cases}$	optimality
2	$\begin{cases} \min s \\ B_i y_i + I s \geq e_i - T_i x^* \\ y_i \geq 0 \\ s \geq 0 \end{cases}$	$\begin{cases} \max \pi^T (e_i - T_i x^*) \\ \pi^T B_i \leq 0 \\ \mathbf{1}^T \pi \leq 1 \\ \pi \geq 0 \end{cases}$	feasibility

Benders cut loop: In-Out techniques



- **Basic idea:**

- Find a point q in the interior of LP relaxation of (or-MILP)
- Given x^* (optimal solution of current master LP), try to separate a point in the segment $[x^*, q]$

- **Goal:**

- Break correlation between separation and optimization
- Accelerate convergence of cut loop

- Proposed by [Ben-Ameur and Neto, 2007] for Network Design Problems

- Also used by [Fischetti et al., 2015] and [Fischetti et al., 2016] for Benders applied to Facility Location

Benders performance evaluation: the test bed

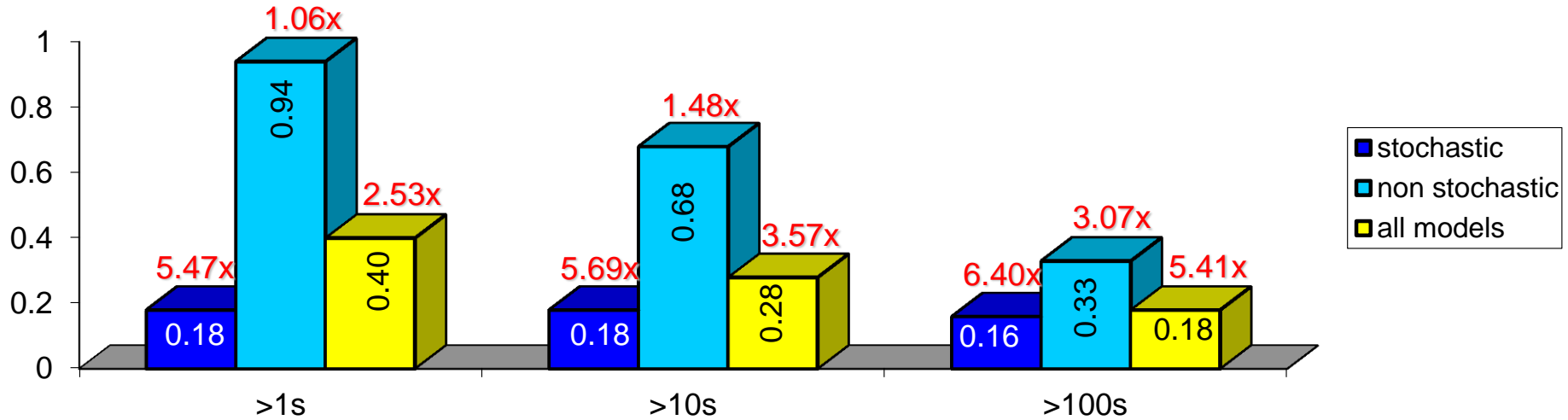
- **Stochastic MILP** (189 models in total)
 - Stochastic Capacitated Facility Location (SCFL)
 - 32 models from [Loveaux, 1986], also used by [Bodur et al., 2016]
 - 50 customers, 25 – 50 facilities, 250 – 500 scenarios
 - Number of non-zeroes after presolve: 560,595 – 2,248,396
 - Stochastic Network Interdiction Problem (SNIP)
 - 70 models, from [Pan and Morton, 2008], also used by [Bodur et al., 2016]
 - 320 binary variables, 456 scenarios, each scenario is a network-LP with 5290 constraints and 830 variables
 - Number of non-zeroes after presolve: 1,827,210 – 1,883,640
 - Stochastic fixed charge multi-commodity network design (SCMND)
 - 70 models from [Crainic et al., 2014]
 - Networks with 60 to 120 vertices and 10 to 40 commodities, 96 or 320 scenarios of demand and varying correlations between the demands of different commodities.
 - Number of non-zeroes after presolve: 197,760 – 2,994,600
 - Stochastic models from our internal library (17 models in total)
 - Unit Commitment, Optimal Power Flow, Network Design

Benders performance evaluation: the test bed

- **Non-stochastic MILP** (201 models in total)
 - Capacitated and Uncapacitated Facility Location (CFL and UFL)
 - 128 models generated as in [\[Fischetti et al., 2015\]](#) and [\[Fischetti et al., 2016\]](#)
 - From 30 facilities and 120 customers (toy models) up to 580 facilities and 2120 customers
 - Number of non-zeroes after presolve: 10,800 – 3,170,986
 - Network Expansion (NEXP)
 - 60 models from [\[Atamturk et al., 2001\]](#)
 - Network expansion problems with step functions capacity installation cost. Networks with between 50 and 150 vertices, 20% edge density and between 2 and 8 steps in the cost function.
 - Number of non-zeroes after presolve: 801 – 40,359
 - From our internal library (13 models in total)
 - Unit Commitment, Long term nuclear power plant maintenance planning, Network Design

CPLEX 12.7.0: Benders B&C performance evaluation

Benders B&C compared to “regular” B&C on all models



	Stochastic			Non stochastic		
	# models	# wins/losses	# timeout (regular B&C / Benders B&C)	# models	# wins/losses	# timeout (regular B&C / Benders B&C)
> 1sec	168	130/37	76/17	152	61/80	6/4
> 10 secs	163	126/37	76/17	86	52/32	6/4
> 100 secs	149	117/32	76/17	44	30/13	6/4

CPLEX 12.7.0: Benders B&C performance evaluation

	Benders B&C on "> 1 sec"					
	# models	# wins / losses	# timeout (regular B&C / Benders B&C)	Benders speedup / slowdown	Regular B&C Secs (geomean)	Benders B&C Secs (geomean)
SNIP	69	69/0	69/0	+28.10x	10,000	355.9
SCFL	32	32/0	1/0	+19.33x	452.3	23.4
SMCND	52	15/37	1/17	-3.60x	235.1	846.8
Other stochastic	15	14/0	5/0	+6.53x	262.2	40.2
NEXP	44	2/40	0/2	-5.50x	6.0	33.0
CFL and UFL	101	57/36	5/0	+2.42x	18.6	7.7
Other non stochastic	7	2/4	1/2	-1.61x	113.5	183.3

- SNIP
 - Unsolvable with regular B&C
 - Benders B&C: All 70 models in > 100 secs, 6 models in > 1k secs, 1 timeout
- SCFL, CFL, UFL
 - Strong LP relaxation, but much harder to solve in the original space
 - Benders cut loop converges very fast and with very few cuts to LP optimum
- SMCND, NEXP
 - Weak LP relaxation, integrality cuts much more effective in the original space, heuristics more effective in the original space
 - Benders cut loop: slow convergence to the LP optimum

CPLEX 12.7.0: Benders B&C performance evaluation

SMCND instances

- A corner case in favor of regular B&C
 - Regular B&C
 - Presolved problem size: # rows / # cols / # nonzeros = 32,160 / 204,060 / 617,760
 - Gap left at the end of root node: **0.01%** w.r.t. optimal solution, 0.33% w.r.t. incumbent solution
 - Problem solved in **3 nodes** and **54.02 secs**
 - Benders B&C
 - Problem size after Benders cut loop: # rows / # cols / # nonzeros = 2,583 / 156 / 84,008
 - Gap left at the end of root node: **8.40%** w.r.t. optimal solution, 14.69% w.r.t. incumbent solution
 - **Branching not effective** (numerical issues): **time limit** (10k secs) hit after **105,934 nodes** with 4.29% gap left
- A corner case in favor of Benders B&C
 - Regular B&C
 - Gap left at the end of root node: **9.39%** w.r.t. optimal solution, 10.96% w.r.t. incumbent solution
 - Problem solved in **1,083 nodes** and **4,958.66 secs**
 - Benders B&C
 - Gap left at the end of root node: **23.34%** w.r.t. optimal solution, 24.30% w.r.t. incumbent solution
 - **Branching is effective**: problem solved in **16,854 nodes** and **370.94 secs**

CPLEX 12.7.0: Benders B&C performance evaluation

▪ SNIP models, an example

– Regular B&C

- Presolved problem size: # rows / # cols / # nonzeros = 761,179 / 128,800 / 1,827,210
- Time to solve the first LP relaxation: 959.10 secs
- Elapsed time at the end of root node: 9,327.62 secs (gap left w.r.t. optimal solution is 15.41%)
- Time limit hit after 4 nodes with 20.77% gap left (w.r.t. best available solution)

– Benders B&C

- Problem size after Benders cut loop: # rows / # cols / # nonzeros = 2,738 / 664 / 6,196
- Elapsed time at the end of root node: 131.7 secs (gap left w.r.t. optimal solution is 31.23%)
- Problem solved in 104,446 nodes and 254.77 secs

CPLEX 12.7.0: Benders B&C performance evaluation

CFL and UFL instances

- Regular B&C is in troubles with more than 240 facilities and 2120 customers:
 - 240 facilities and 2120 customers: 1 instance solved in 728.7 secs, 3 instances solved in more than 1k secs, 1 time limit
 - 580 facilities and 2120 customers: 1 instance solved in 960.4 secs, 4 out of memory
- Benders B&C solves all the above 10 instances with time varying from 34.4 to 72.6 secs
- UFL, an instance with 240 facilities and 2120 customers
 - Regular B&C
 - Presolved problem size: # rows / # cols / # nonzeroes = 489,600 / 489,839 / 1,464,720
 - Time to solve the first LP relaxation: 164.12 secs
 - Elapsed time at the end of root node: 289.33 secs (gap left w.r.t. optimal solution is 5.42%)
 - Time limit hit after 2,511 nodes with a gap left of 1.42% (w.r.t. best available solution)
 - Benders B&C
 - Problem size after Benders cut loop: # rows / # cols / # nonzeroes = 1,637 / 2,279 / 17,578
 - Elapsed time at the end of root node: 36.6 secs (gap left w.r.t. optimal solution is 5.42%)
 - Problem solved in 17,928 nodes and 72.61 secs

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